

TOPIC 13. DIFFERENTIALS, GRAD, CURL, DIV

1. Differential forms.

All functions will be infinitely differentiable defined on some open subset U of \mathbb{R}^3 , for instance

$$U = \{(x, y, z) : x^2 + y^2 + z^2 < 1\}.$$

We will deal with vector spaces $\Omega^0, \Omega^1, \Omega^2, \Omega^3$ defined as follows:

Ω^0 : The vector space consisting of all (infinitely differentiable) functions $f : U \rightarrow \mathbb{R}$.

Ω^1 : The vector space of differential 1-forms. These are expressions $f dx + g dy + h dz$, where $f, g, h : U \rightarrow \mathbb{R}$ are functions.

Ω^2 : All differential 2-forms, expressions $f dx \wedge dy + g dx \wedge dz + h dy \wedge dz$, where again $f, g, h : U \rightarrow \mathbb{R}$ are functions.

Ω^3 : Differential 3-forms, expressions $f dx \wedge dy \wedge dz$, where $f : U \rightarrow \mathbb{R}$ is a function.

For a given k -form α , the number k is its degree. If $\alpha \in \Omega^k$ we say that α is a k -form. Collectively all these elements are differential forms. The symbol \wedge is read wedge. It represents the wedge product.

2. Algebraic rules.

The rules for manipulating these are as follows. You can add functions (0-differential forms) and multiply them the usual way. You can add forms of the same degree: just collect terms if and when convenient. You can multiply functions times 1-forms just distributing the product over the sum:

$$p(f dx + g dy + h dz) = pf dx + pg dy + ph dz$$

Likewise functions times 2-forms or 3-forms (in the latter case trivially).

More generally you can multiply forms of some degree times forms of the same or another degree freely, writing for instance $\alpha \wedge \beta$ for the product of α and β . The rules for this kind of multiplication allow for distributivity of product over sum, as in

$$(\alpha_1 + \alpha_2) \wedge \beta = \alpha_1 \wedge \beta + \alpha_2 \wedge \beta.$$

However, \wedge has the property that if α and β are 1-forms, then $\alpha \wedge \beta = -\beta \wedge \alpha$. For example, $dx \wedge dy = -dy \wedge dx$. In general, \wedge is distributive and associative, but not commutative

3. Differentiation

There are operators from Ω^k to Ω^{k+1} , all denoted d , as follows.

(0) The differential of a 0-form $f \in \Omega^0$ (a function) is

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz.$$

(1) The differential of a 1-form $\alpha = f dx + g dy + h dz$ is computed using the differentials of the coefficients and the wedge product:

$$d\alpha = df \wedge dx + dg \wedge dy + dh \wedge dz$$

(2) Similarly, if $\alpha = f dx \wedge dy + g dx \wedge dz + h dy \wedge dz$ (a 2-form):

$$d\alpha = df \wedge dx \wedge dy + dg \wedge dx \wedge dz + dh \wedge dy \wedge dz$$

(3) Finally, if $\alpha = f dx \wedge dy \wedge dz$, then $d\alpha = 0$.

13.1. Computations using the differential.

(i) Let $\alpha = f dx + g dy + h dz$, an element of Ω^1 . Compute

$$d\alpha - \left[\left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy + \left(\frac{\partial h}{\partial x} - \frac{\partial f}{\partial z} \right) dx \wedge dz + \left(\frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) dy \wedge dz \right]$$

(ii) Let $\alpha = f dx \wedge dy + g dx \wedge dz + h dy \wedge dz$. Compute $d\alpha$. The result is a function times $dx \wedge dy \wedge dz$.

(iii) Let f be a function, α a differential 1-form. Compute $d(f\alpha)$.

(iv) For each of $k = 0, 1, 2, 3$, let $\alpha \in \Omega^k$. Compute $d(d\alpha)$.

(v) Let α and β be 1-forms. Compute

$$d(\alpha \wedge \beta) - [(d\alpha) \wedge \beta - \alpha \wedge d\beta]$$

(vi) Let $\alpha \in \Omega^1$, $\beta \in \Omega^2$. Compute

$$\alpha \wedge \beta - \beta \wedge \alpha.$$

4. \star operator.

In the next problems we use an operator, denoted \star (the Hodge star operator, called star for short), that takes a k -form and produces a $(3-k)$ -form. It has the following properties:

(a) If α and β are differential forms of the same degree and f and g are functions, then $\star(f\alpha + g\beta) = f\star\alpha + g\star\beta$.

(b) Furthermore,

$$\begin{cases} \star(1) = dx \wedge dy \wedge dz \\ \star dx = dy \wedge dz, \star dy = dz \wedge dx, \star dz = dx \wedge dy \\ \star(dy \wedge dz) = dx, \star(dz \wedge dx) = dy, \star(dx \wedge dy) = dz \\ \star(dx \wedge dy \wedge dz) = 1. \end{cases}$$

The 1 should be viewed as the constant function 1.

13.2. These problems will give you some practice on how \star works:

(i) As a warm up exercise, compute $\star\alpha$ for α an arbitrary k -form (do $k = 0, 1, 2, 3$).

(ii) Let α be a k -form. Compute $\star d\alpha$ and $d\star\alpha$.

(iii) Let f be a function. Compute $\star d\star df$.

5. From vector fields to 1-forms and back.

In the following problem we pass from vector fields to differential 1-forms and back via the following procedure: Given the vector field $V = f\mathbf{i} + g\mathbf{j} + h\mathbf{k}$, construct a differential 1-form by the rule

$$F(f\mathbf{i} + g\mathbf{j} + h\mathbf{k}) = f dx + g dy + h dz.$$

The inverse procedure produces a vector field starting with a 1-form.

13.3. Grad, curl, div.

(i) Let f be a function. Compute $F^{-1}(df)$.

(ii) Let $V = f\mathbf{i} + g\mathbf{j} + h\mathbf{k}$. Compute

$$F^{-1}\star dF(V)$$

explicitly. Note that $F(V)$ is a 1-form, $dF(V)$ is a 2-form, $\star dF(V)$ is again a 1-form, and $F^{-1}\star dF(V)$ is vector field.

(iii) Let $V = f\mathbf{i} + g\mathbf{j} + h\mathbf{k}$. Compute

$$\star d\star F(V).$$

(iv) Write formulas for grad, curl, and div using F , \star , and d .